



National Aeronautics and  
Space Administration

Jet Propulsion Laboratory  
California Institute of Technology  
Pasadena, California

# Compatibility Tests Between the Mars Vehicle System Test Bed and RIMFAX Radar Antenna Prototype for the Mars 2020 Mission

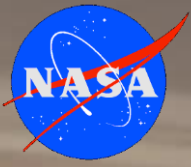
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*Forsvarets forskningsinstitutt*

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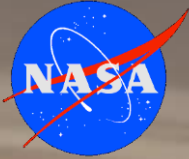




# Mars 2020 Rover

SAMPLE AND CACHE  
HABITABILITY  
EVIDENCE OF LIFE  
PREPARE FOR HUMANS





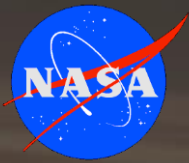
# Mars 2020 Rover

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## INSTRUMENTS

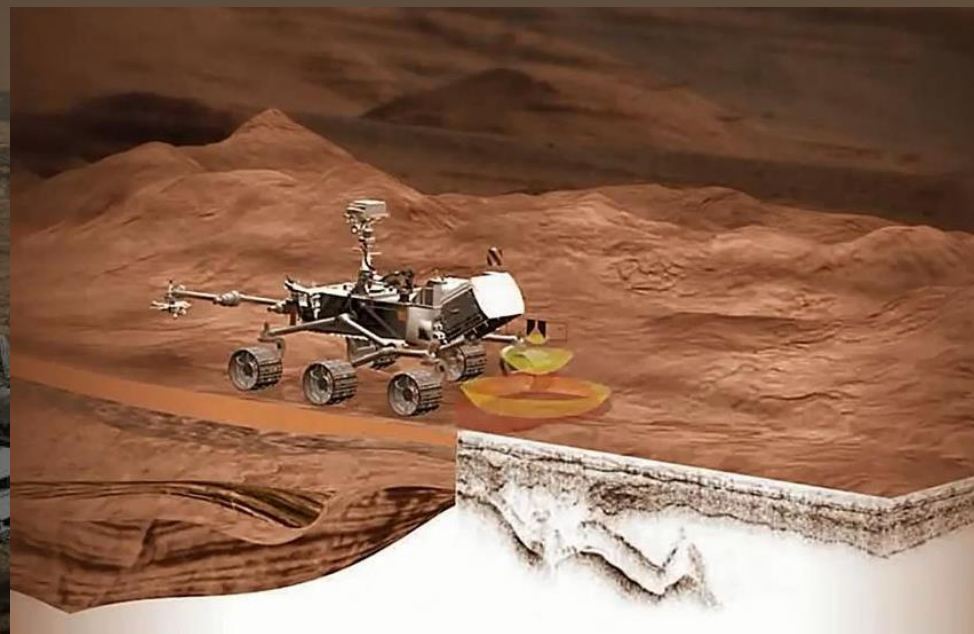
SuperCam  
MastCam-Z  
SHERLOC  
PIXL  
MOXIE  
MEDA  
**RIMFAX**

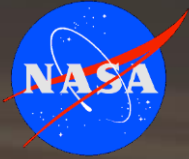




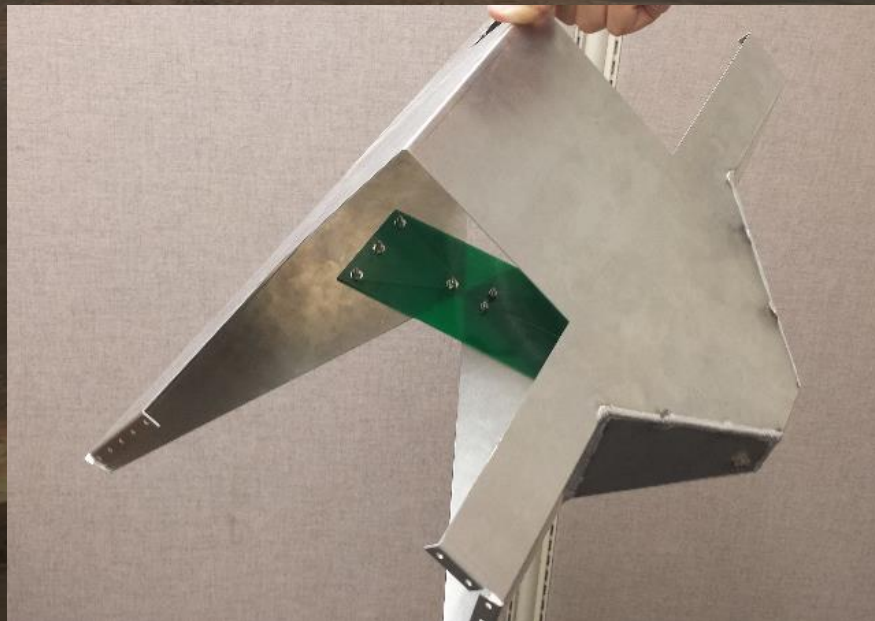
# RIMFAX

- Radar Imager for Mars' subsurFace eXperiment
- UWB ground penetrating radar (GPR)
- Goal: analyze shallow and deep subsurface structure and composition
- 150 MHz to 1200 MHz



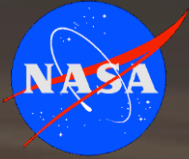


# Compatibility concerns



- Rover is a complex electronic system with dozens of subsystems, each generating noise
- RIMFAX is a sensitive GPR with strict scientific requirements
- Risk magnified as RIMFAX will operate during rover driving (i.e. operating many avionics subsystems concurrently)
- Will science impose additional EMC requirements?
- RIMFAX team offered prototype antenna for risk reduction tests



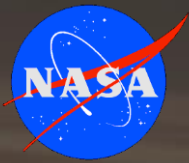


# Test proposal

- JPL proposed tests using most accurate test bed available: Vehicle System Test Bed (VSTB) at JPL's Mars Yard.
- Place prototype antenna in proposed rover location
- Drive rover at high and low speeds (4.2 cm/s and 2.1 cm/s, respectively) while measuring received signal with spectrum analyzer emulating radar



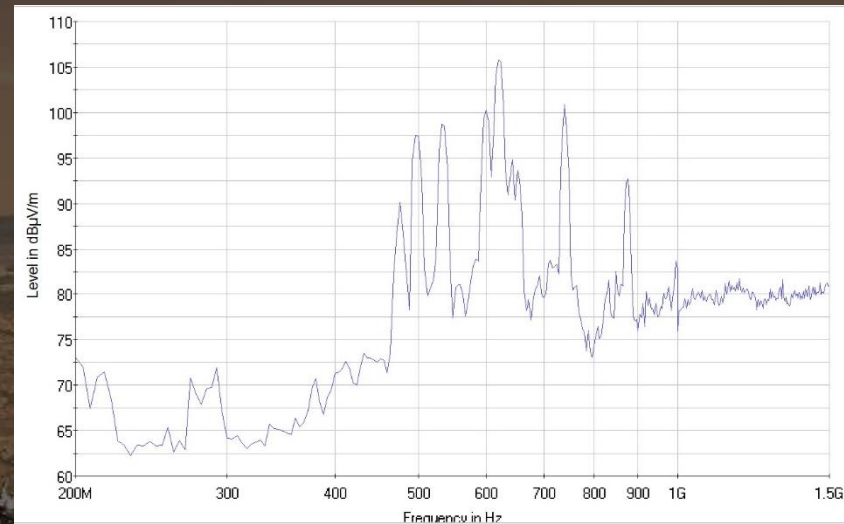


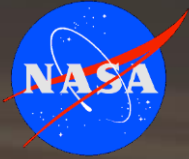


# Test challenges

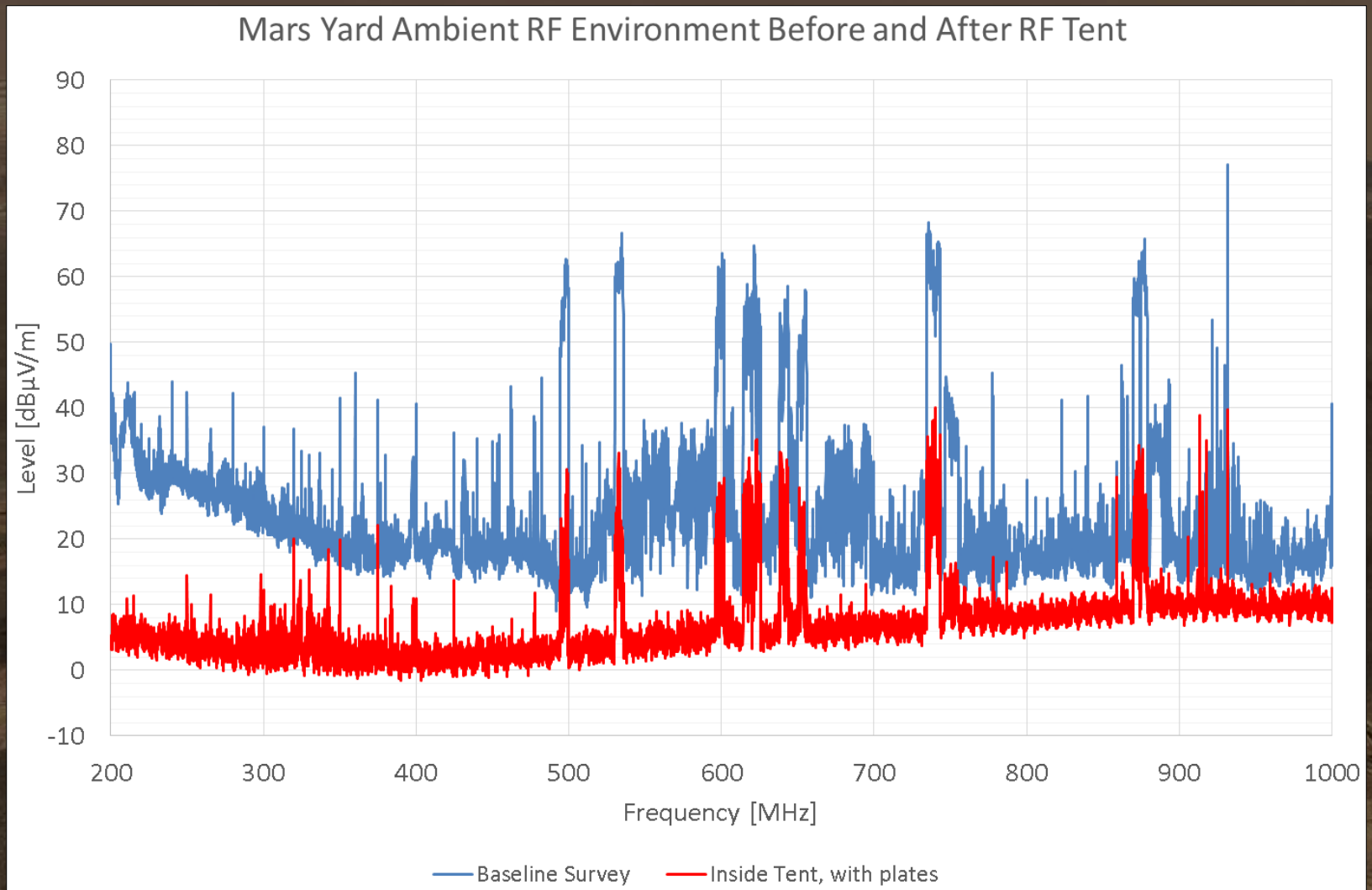
- JPL is close to TV transmitters serving much of Los Angeles. These occupy much of the operating range of RIMFAX
- VSTB has environmental and hardware safety restrictions.

➔ Custom RF tent built to fit in confines of garage

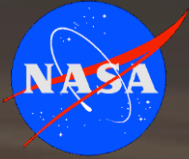




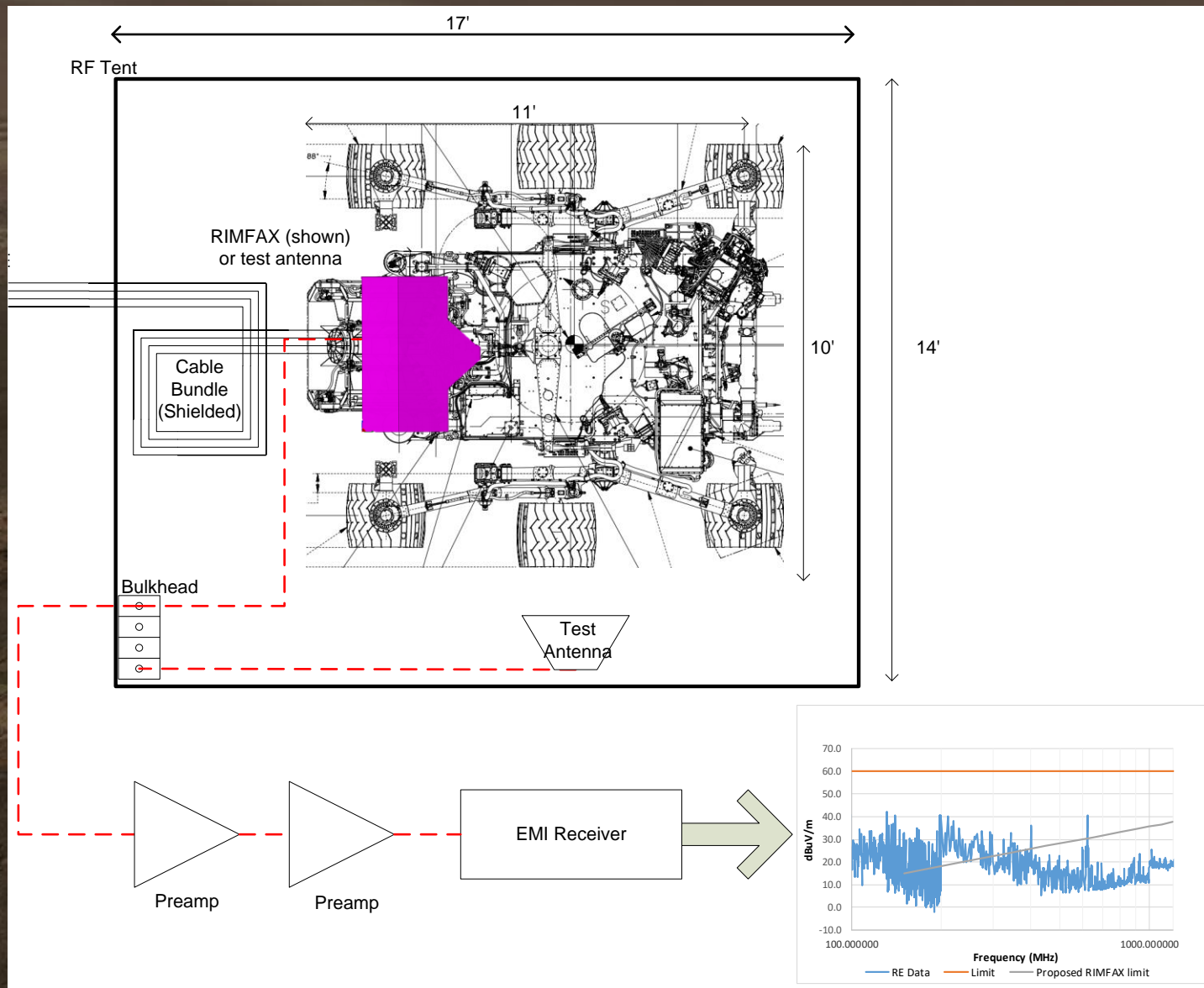
# Verification of Tent Performance

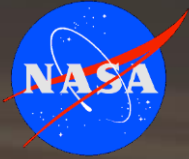




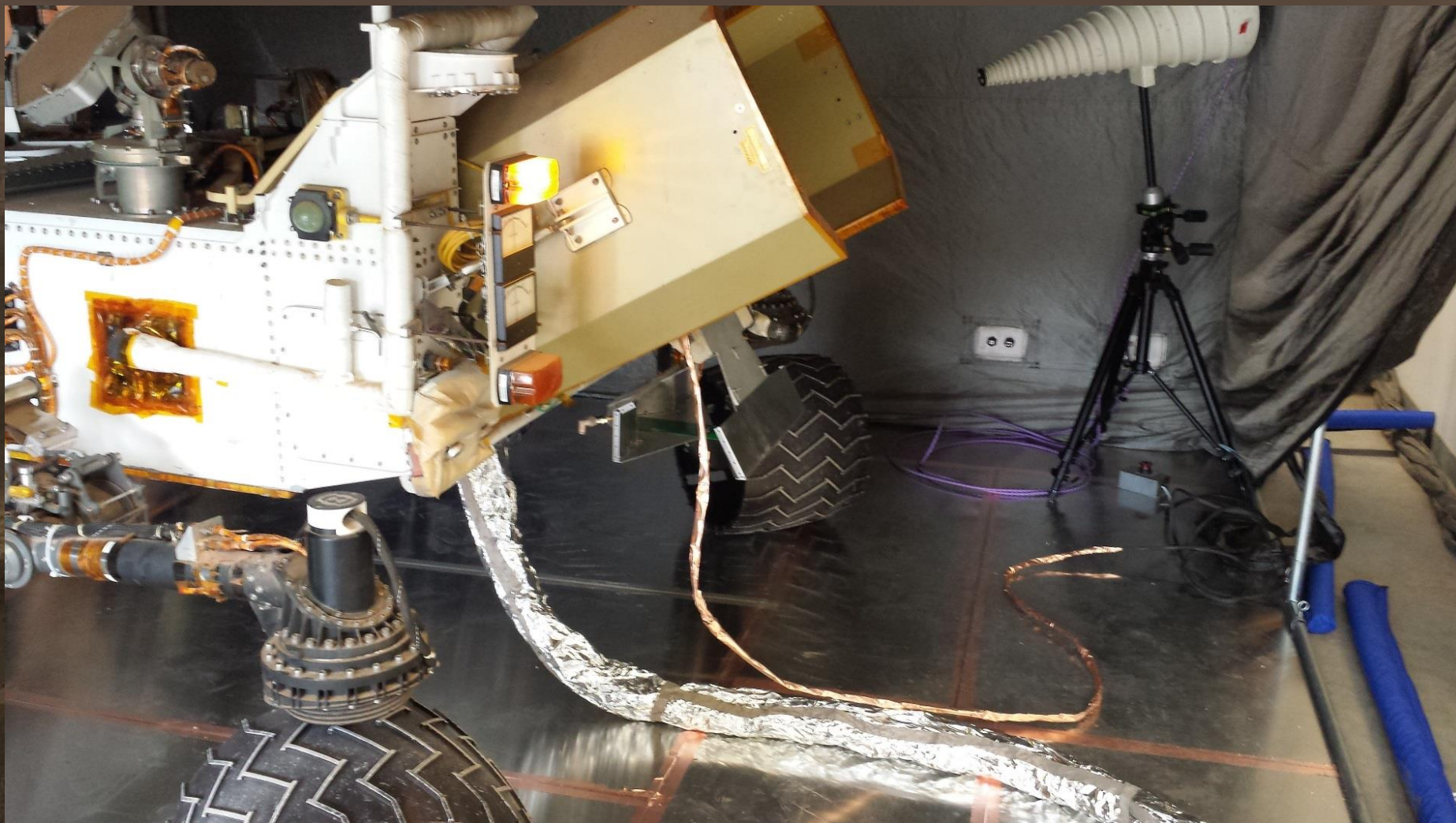


# Test setup

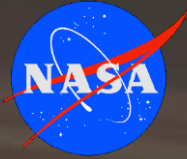




# Test setup







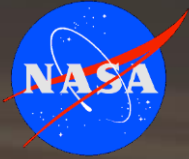
# Receiver settings

TABLE 1. ACTUAL RIMFAX SOUNDING MODE PARAMETERS (TABLE BY FFI)

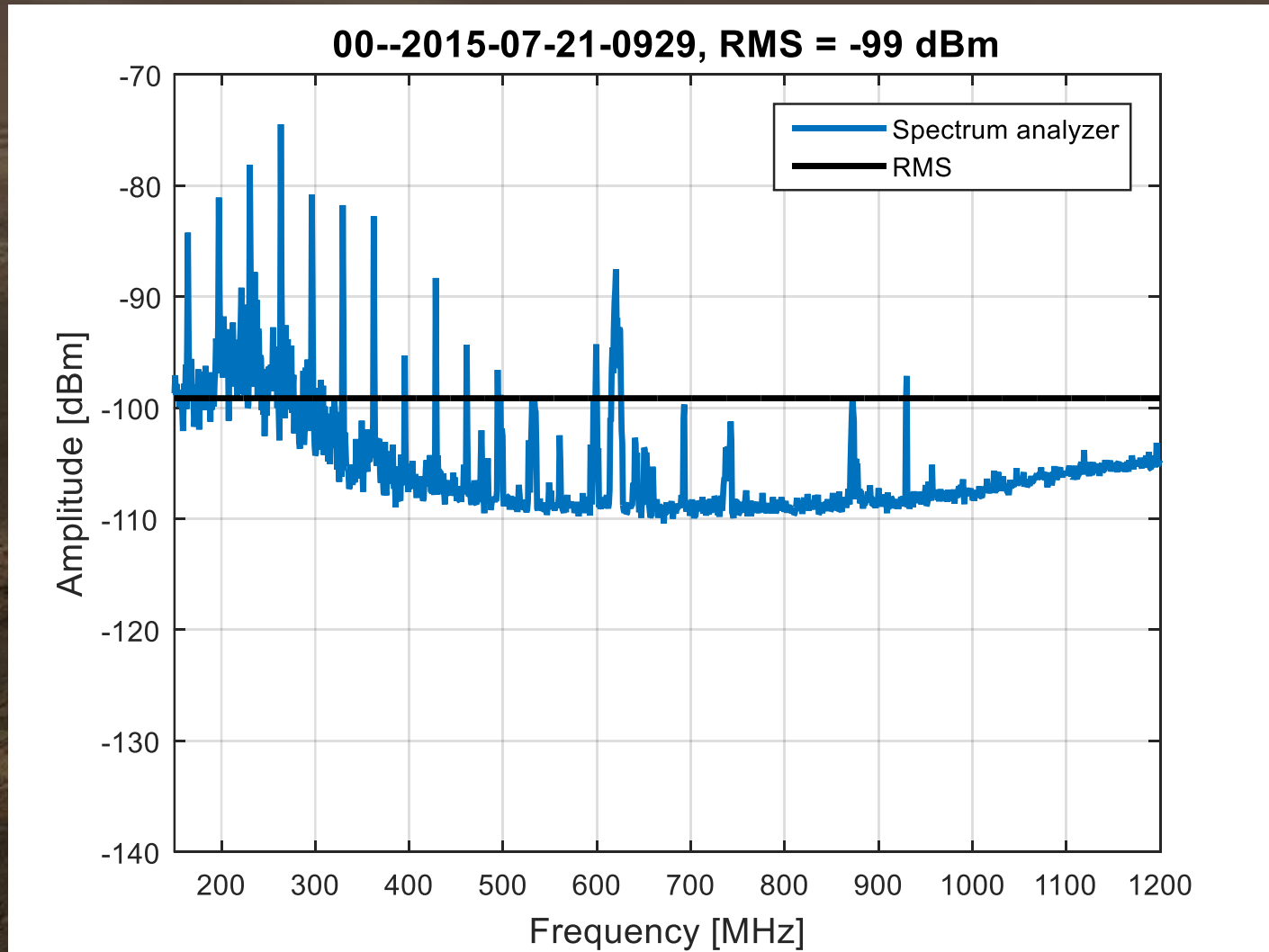
RIMFAX Sounding Modes					
Mode Name	Frequency band (MHz)	Sweep time (ms)	Sweeps averaged per sounding location	<u>Samples after downsampling</u>	IF BW (kHz)
Shallow Sounding	150-1200	1.0	100	1450	725
Deep Sounding	150-450	2.5	40	1250	250
Deep Sounding Ex 2	150-450	20	5	3500	87.5

TABLE 2. ACHIEVABLE RIMFAX PARAMETERS WITH RECEIVER

Test Receiver Settings					
Mode Name	Frequency band (MHz)	Sweep time (ms)	Sweeps averaged per sounding location	<u>Samples after downsampling</u>	IF BW (kHz)
Shallow Sounding	150-1200	10	10	1401	500
Deep Sounding	150-450	10	10	1251	300
Deep Sounding Ex 2	150-450	20	5	3501	50

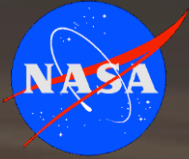


# Results: Shallow Sounding Mode

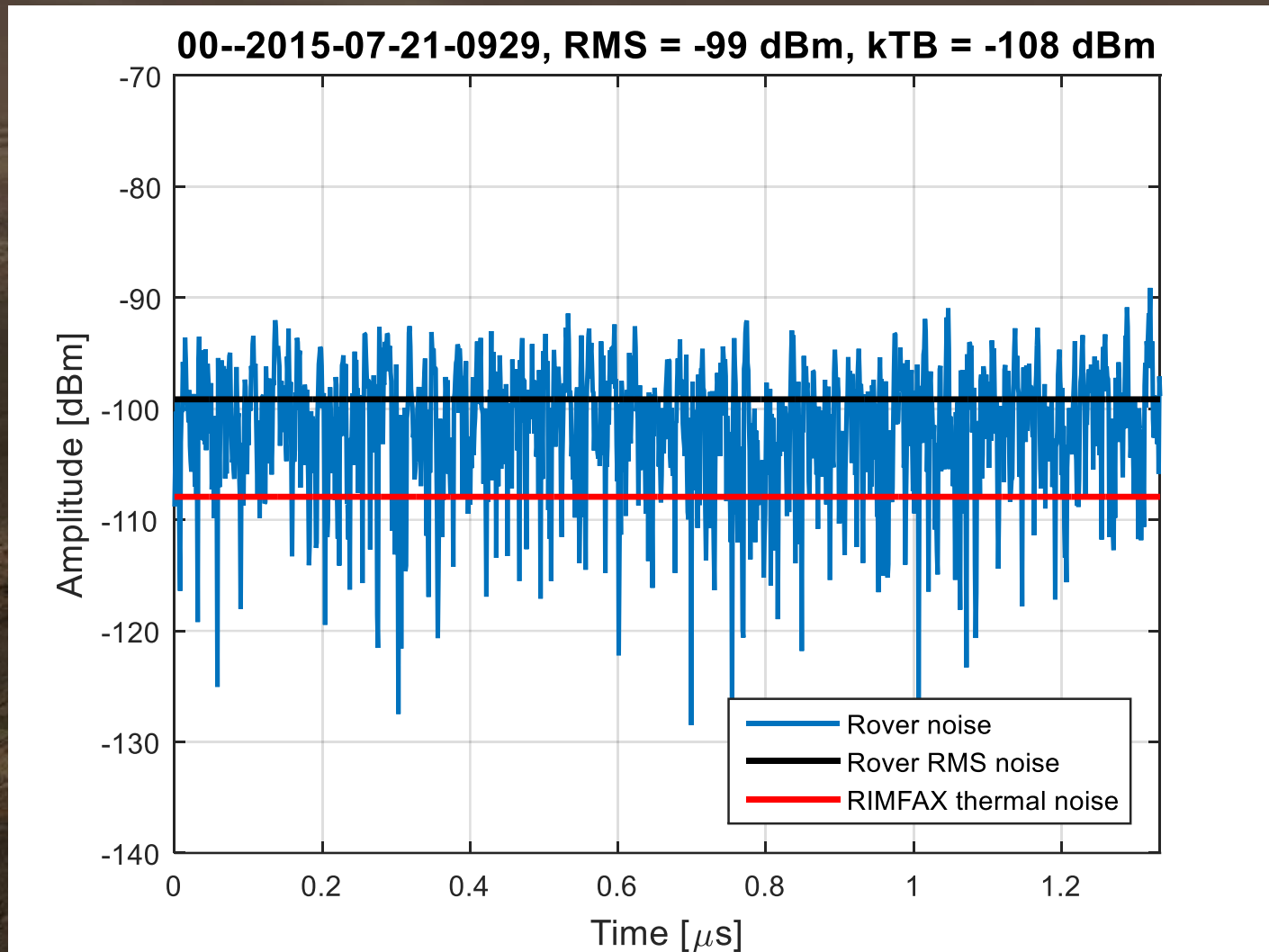


Signal received by RIMFAX prototype antenna in “shallow sounding like” mode

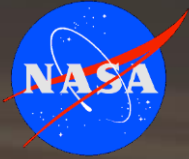




# Results: Shallow Sounding Mode: Time Domain



Random phase assigned to frequency, IFFT to time domain

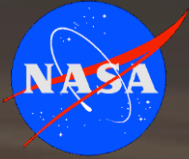


# UWB radar figure of merit: SDR

- EMC RE requirements are often specified based on noise-limited receiver sensitivity.
- Based on previous slides, this limit is exceeded
- Science requirements based on UWB radar figure of merit called signal dynamic range (SDR)

$$SDR = \frac{P_T N_F G^2}{2k_B T_0 F B_{IF} (SNR)}$$

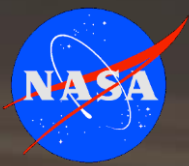




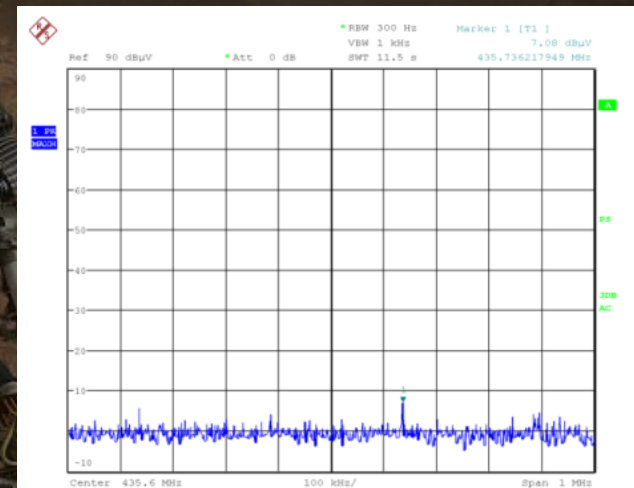
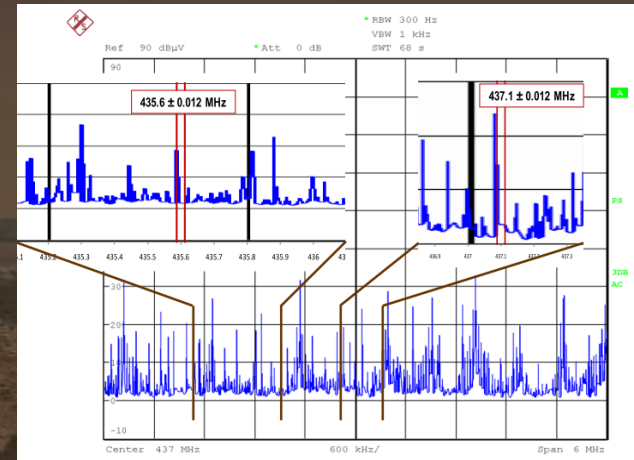
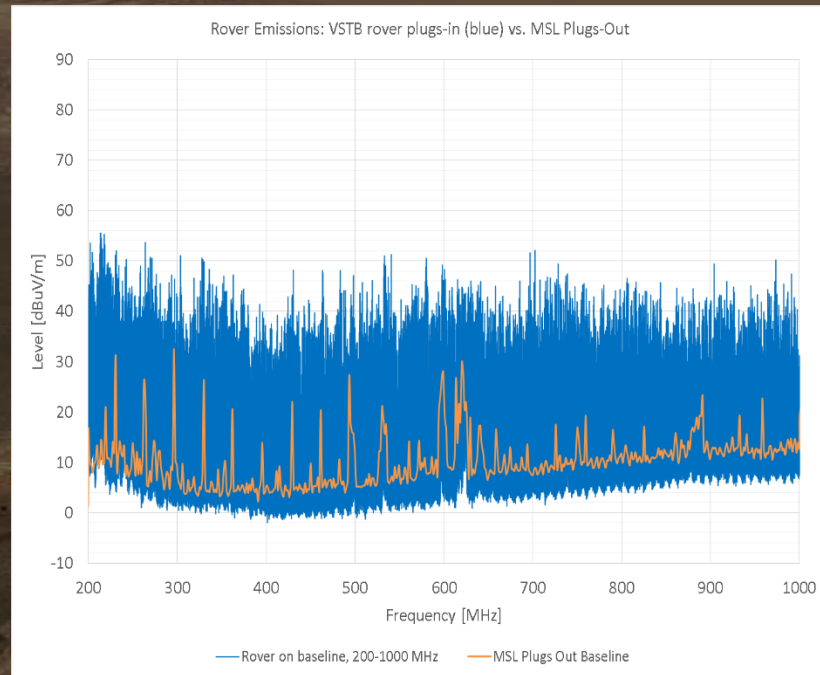
# UWB radar figure of merit: SDR

$$SDR = \frac{P_T N_F G^2}{2k_B T_0 F B_{IF} (SNR)}$$

- The effect of exceeding the baseline thermal noise limit is accounted for by an increase in effective system noise temperature  $T_0$
- However, overall SDR shows that there is in fact 40 dB of margin due to numerous integration points  $N_F$  in FMCW radar sweep

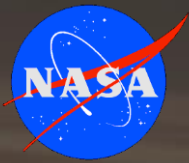


# Comparison to MSL “Curiosity” and plugs-in condition



On top of existing 40 dB margin from SDR, plugs-in (GSE umbilical connected) is a known worst-case situation both from a fundamental EMC condition and from prior experience on the MSL Curiosity rover





# Conclusion

- The RIMFAX UWB ground penetrating radar should provide new insight into the Martian subsurface environment
- The challenges presented rover noise were tested in a controlled RF environment
- Risk to science data from rover noise is expected to be low based on figures of merit used by science team
- Standard EMC figures of merit may not be appropriate for all potential victims